

## Ordering method

### TS-S2/TS-SH (TRANSERVO)

<b>Robot positioner</b>	<b>Type</b>	<b>I/O</b>	<b>Battery <sup>Note 1</sup></b>
S2: TS-S2	No entry: Standard	NP: NPN	B: With battery (Absolute model)
SH: TS-SH	S: Sensor	PN: PNP	N: None (Incremental model)
		CC: CC-Link	
		DN: DeviceNet™	
		EP: EtherNet/IP™	
		PT: PROFINET	
		GW: With no I/O board	

Note 1. Battery can only be selected for TS-SH. (Not provided for TS-S2).

### TS-X/TS-P (FLIP-X/PHASER)

<b>Controller</b>	<b>Driver: Power-supply voltage/ Power capacity</b>	<b>Regenerative unit</b>	<b>LCD monitor</b>	<b>Input/Output Selection</b>	<b>Battery <sup>Note 2</sup></b>
TSX: TS-X	105: 100V / 100W more less	No entry: None	No entry: None	NP: NPN	B: With battery (Absolute model)
TSP: TS-P	110: 100V / 200W	R: With RGT	L: With LCD	PN: PNP	N: None (Incremental model)
	205: 200V / 100W more less	R: With RGU-2		CC: CC-Link	
	210: 200V / 200W			DN: DeviceNet™	
	220: 200V / 400 to 600W			EP: EtherNet/IP™	
				PT: PROFINET	
				GW: With no I/O board	

Note 2. Battery can only be selected for TS-X. (Not provided for TS-P).