YK610XE-10

Standard type: Medium type

LOW COST HIGH PERFORMANCE MODEL

Arm length 610mm **Maximum payload 10kg**

Ordering method

YK610XE - 10 - 200 [ ] [ ] [ ] - RCX340-4 [ ] [ ] [ ] [ ] [ ] [ ] [ ]

Model	Maximum payload	Z axis stroke	Tool flange	Hollow shaft	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
			No entry: None F: With tool flange	No entry: None S: With hollow shaft	3L: 3.5m 5L: 5m 10L: 10m								

Specify various controller setting items. RCX340 ▶ P.566

Note. The return-to-origin method is provided only in the sensor specifications, but not in the stroke end specifications.

Specifications

			X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length		335 mm	275 mm	200 mm	-
	Rotation angle		+/-134 °	+/-152 °	-	+/-360 °
AC servo motor output			400 W	200 W	200 W	200 W
Deceleration mechanism	Transmission method	Motor to speed reducer	Direct-coupled		Timing belt	
		Speed reducer to output	Direct-coupled			Timing belt
Repeatability Note 1			+/-0.01 mm		+/-0.01 mm	+/-0.01 °
Maximum speed			8.6 m/sec		2 m/sec	2600 °/sec
Maximum payload			10 kg (Standard specification), 9 kg (Option specifications Note 4)			
Standard cycle time: with 2kg payload Note 2			0.39 sec			
R-axis tolerable moment of inertia Note 3			0.3 kgm^2			
User wiring			0.2 sq × 20 wires			
User tubing (Outer diameter)			φ 6 × 3			
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length			Standard: 3.5 m Option: 5 m, 10 m			
Weight			25 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions and performing the coarse positioning arch operation.
Note 3. The acceleration coefficient is set automatically in accordance with the tip weight and offset amount for R-axis moment of inertia settings.
Note 4. Maximum payload of option specifications (with user wiring/tubing through spline type) is 9kg.

Controller

Controller	Power capacity (VA)	Operation method
RCX340	1700	Programming / Remote command / Operation using RS-232C communication

Note. The movement range can be restricted by adding the X- and Y-axis mechanical stoppers. (The maximum movement range was set at shipment.)
See our robot manuals (installation manuals) for detailed information.
Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
https://global.yamaha-motor.com/business/robot/

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