## YP320X 2axes

Ordering method



RCX222 Controller - Usable for CE - I/O selection 1 - I/O selection 2

Specify various controller setting items. RCX222 ▶ P.558

	X axis	Z axis
AC servo motor output (W)	200	200
Repeatability Note 1 (mm)	+/-0.02	+/-0.05
Drive system	Ball screw ф15	Timing belt
Deceleration ratio (mm)	Equivalent to lead 20	Equivalent to lead 25
Maximum speed Note 2 (mm/sec)	1500	1500
Moving range (mm)	330	100
Cycle time (sec)	0.57 Note 3, 0.78 Note 4	
Maximum payload (kg)	3	
Robot cable length (m)	Standard: 3.5 Option: 5,10	
Weight (kg)	21	

■ Controller Power consumption (VA) Controller Operating method Programming / I/O point trace / Remote command / RCX320 RCX222 500 Operation using RS-232C communication

- Note 1. Positioning repeatability precision in a single swing when residual vibration is stabilized (variable depending on the load and stroke).

  Note 2. When the moving stroke is short, the maximum speed may not be reached.

  Note 3. Reciprocating time in vertical direction (50mm) and longitudinal direction (150mm) with the arch amount of 50 (when executing roughpositioning arch motion with 1kg load).

  Note 4. Reciprocating time in vertical direction (25mm) and longitudinal direction (300mm) with the arch amount of 25 (when executing roughpositioning arch motion with 1kg load).
- positioning arch motion with 1kg load)

